

AmZ8136

Eight-Bit Decoder With Control Storage

DISTINCTIVE CHARACTERISTICS

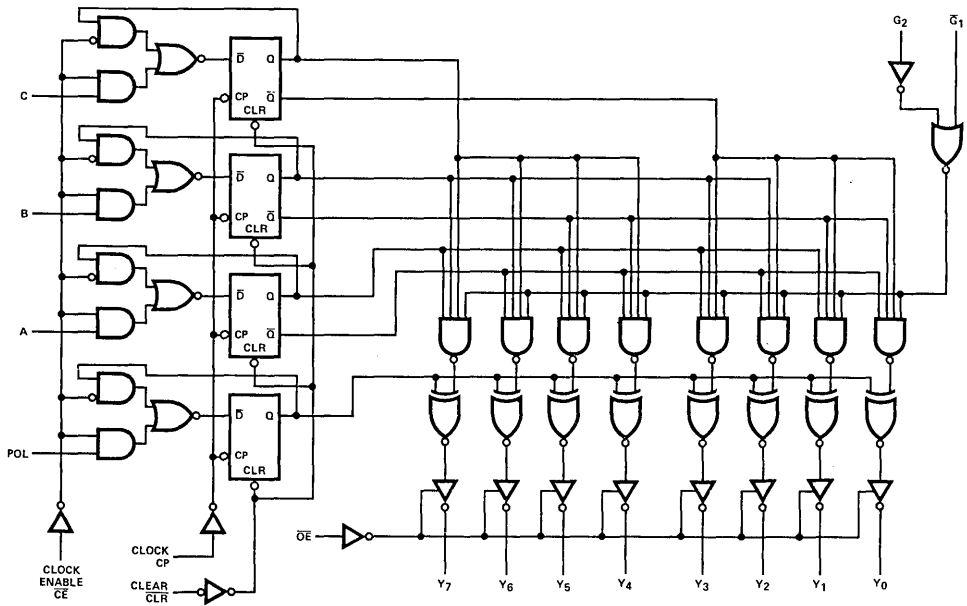
- 8-bit decoder/demultiplexer with control storage
- 3-state outputs
- Common clock enable
- Common clear
- Polarity control
- Advanced Low Power Schottky Process
- 100% product assurance screening to MIL-STD-883 requirements

FUNCTIONAL DESCRIPTION

The AmZ8136 is an eight-bit decoder with control storage. It provides a conventional 8-bit decoder function with two enable inputs which may also be used for data input. This can be used to implement a demultiplexer function. In addition, the "exclusive-OR" gates provide polarity control of the selected output. The 3-state outputs are enabled by an active LOW input on the output enable, \overline{OE} .

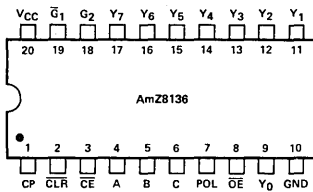
The three control bits representing the output selection and the single bit polarity control are stored in "D" type flip-flops. These flip-flops have Clear, Clock, and Clock Enable functions provided. The \overline{G}_1 and G_2 inputs provide either polarity for input control or data.

LOGIC DIAGRAM
8-Bit Decoder/Demultiplexer with Control Storage



BLI-190

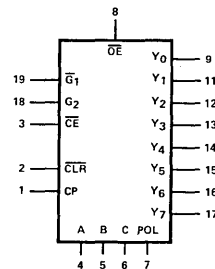
CONNECTION DIAGRAM



Note: Pin 1 is marked for orientation.

BLI-191

LOGIC SYMBOL



$V_{CC} = 20$
 $GND = 10$

BLI-192

ELECTRICAL CHARACTERISTICS

The Following Conditions Apply Unless Otherwise Specified:

COM'L $T_A = 0^\circ\text{C to } +70^\circ\text{C}$ $V_{CC} = 5.0\text{V} \pm 5\%$ MIN. = 4.75 V MAX. = 5.25 VMIL $T_A = -55^\circ\text{C to } +125^\circ\text{C}$ $V_{CC} = 5.0\text{V} \pm 10\%$ MIN. = 4.50 V MAX. = 5.50 V**DC CHARACTERISTICS OVER OPERATING RANGE**

Parameters	Description	Test Conditions (Note 1)	Min.	Typ. (Note 2)	Max.	Units	
V_{OH}	Output HIGH Voltage	$V_{CC} = \text{MIN.}$ $V_{IN} = V_{IH} \text{ or } V_{IL}$	$I_{OH} = -2.6\text{mA, COM'L}$	2.4	3.2	Volts	
			$I_{OH} = -1.0\text{mA, MIL}$	2.4	3.4		
V_{OL}	Output LOW Voltage	$V_{CC} = \text{MIN.}$ $V_{IN} = V_{IH} \text{ or } V_{IL}$	$I_{OL} = 24\text{mA, COM'L}$		0.4	0.5	Volts
			$I_{OL} = 12\text{mA, MIL}$		0.35	0.4	
V_{IH}	Input HIGH Level	Guaranteed input logical HIGH voltage for all inputs		2.0		Volts	
V_{IL}	Input LOW Level	Guaranteed input logical LOW voltage for all inputs	MIL		0.7	Volts	
			COM'L		0.8		
V_I	Input Clamp Voltage	$V_{CC} = \text{MIN.}, I_{IN} = -18\text{mA}$			-1.5	Volts	
I_{IL}	Input LOW Current	$V_{CC} = \text{MAX.}, V_{IN} = 0.4\text{V}$			-0.4	mA	
I_{IH}	Input HIGH Current	$V_{CC} = \text{MAX.}, V_{IN} = 2.7\text{V}$			20	μA	
I_I	Input HIGH Current	$V_{CC} = \text{MAX.}, V_{IN} = 7.0\text{V}$			0.1	mA	
I_O	Off-State (High-Impedance) Output Current	$V_{CC} = \text{MAX.}$	$V_O = 0.4\text{V}$		-20	μA	
			$V_O = 2.4\text{V}$		20		
I_{SC}	Output Short Circuit Current (Note 3)	$V_{CC} = \text{MAX.}$		-15	-85	mA	
I_{CC}	Power Supply Current (Note 4)	$V_{CC} = \text{MAX.}$			37	56	mA

Notes: 1. For conditions shown as MIN, or MAX., use the appropriate value specified under Electrical Characteristics for the applicable device type.

2. Typical limits are at $V_{CC} = 5.0\text{V}$, 25°C ambient and maximum loading.

3. Not more than one output should be shorted at a time. Duration of the short circuit test should not exceed one second.

4. Test Conditions: A = B = C = $\overline{G_1}$ = G_2 = \overline{OE} = \overline{CE} = GND; CLK = CLR = POL = 4.5 V.

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MAXIMUM RATINGS (Above which the useful life may be impaired)

Storage Temperature	-65°C to +150°C
Temperature (Ambient) Under Bias	-55°C to +125°C
Supply Voltage to Ground Potential Continuous	-0.5V to +7.0V
DC Voltage Applied to Outputs for High Output State	-0.5V to + V_{CC} max.
DC Input Voltage	-0.5V to +7.0V
DC Output Current, Into Outputs	30mA
DC Input Current	-30mA to +5.0mA

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SWITCHING CHARACTERISTICS

(T_A = +25°C, V_{CC} = 5.0V)

Parameters	Description	Min.	Typ.	Max.	Units	Test Conditions
t _{PLH}	\overline{G}_1 to Y ₀ - Y ₇		17	25	ns	C _L = 45pF R _L = 667Ω
t _{PHL}			23	34		
t _{PLH}	G ₂ to Y ₀ - Y ₇		20	30	ns	
t _{PHL}			26	39		
t _{PLH}	CP to Y ₀ - Y ₇		24	36	ns	
t _{PHL}			30	45		
t _{PLH}	\overline{CLR} to Y ₀ - Y ₇		24	36	ns	
t _{PHL}			31	46		
t _s	\overline{CE} to CP	25			ns	
t _h		0				
t _s	A, B, C, POL to CP	15			ns	
t _h		0				
t _{HZ}	\overline{OE} to Y ₀ - Y ₇		9	14	ns	C _L = 5pF R _L = 667Ω
t _{LZ}			11	17		
t _{ZH}	\overline{OE} to Y ₀ - Y ₇		15	22	ns	C _L = 45pF R _L = 667Ω
t _{ZL}			16	24		
t _s	Set-up Time, Clear Recovery to CP	20			ns	
t _{pw}	Pulse Width	Clock	15		ns	
		Clear	15			

SWITCHING CHARACTERISTICS
OVER OPERATING RANGE*

Parameters	Description	COM'L		MIL		Units	Test Conditions
		T _A = 0°C to +70°C V _{CC} = 5.0V ±5%		T _A = -55°C to +125°C V _{CC} = 5.0V ±10%			
		Min.	Max.	Min.	Max.		
t _{PLH}	\overline{G}_1 to Y ₀ - Y ₇		29		31	ns	C _L = 45pF R _L = 667Ω
t _{PHL}			39		42		
t _{PLH}	G ₂ to Y ₀ - Y ₇		34		37	ns	
t _{PHL}			44		48		
t _{PLH}	CP to Y ₀ - Y ₇		40		42	ns	
t _{PHL}			51		55		
t _{PLH}	\overline{CLR} to Y ₀ - Y ₇		47		54	ns	
t _{PHL}			58		66		
t _s	\overline{OE} to CP	27		30		ns	
t _h		0		0			
t _s	A, B, C, POL to CP	17		20		ns	
t _h		0		0			
t _{HZ}	\overline{OE} to Y ₀ - Y ₇		17		18	ns	C _L = 5.0pF R _L = 667Ω
t _{LZ}			27		34		
t _{ZH}	\overline{OE} to Y ₀ - Y ₇		25		27	ns	C _L = 5.0pF R _L = 667Ω
t _{ZL}			28		30		
t _s	Set-up Time, Clear Recovery to CP	23		25		ns	
t _{pw}	Pulse Width	Clock	17		20	ns	
		Clear	15		15		

*AC performance over the operating temperature range is guaranteed by testing defined in Group A, Subgroup 9.

FUNCTION TABLE

Mode	Inputs								Internal Registers				Three-State Outputs								
	C	B	A	POL	\overline{CE}	\overline{CLR}	G*	\overline{OE}	CP	QC	QB	QA	QPOL	Y0	Y1	Y2	Y3	Y4	Y5	Y6	Y7
Clear	X	X	X	X	X	L	L	L	X	L	L	L	L	H	H	H	H	H	H	H	H
	X	X	X	X	X	L	H	L	X	L	L	L	L	L	H	H	H	H	H	H	H
Hold	X	X	X	X	H	H	NC	L	↑	NC	NC	NC	NC	NC	NC	NC	NC	NC	NC	NC	NC
Select	L	L	L	H	L	H	H	L	↑	L	L	L	H	H	L	L	L	L	L	L	L
	L	L	H	H	L	H	H	L	↑	L	L	H	H	L	H	L	L	L	L	L	L
	L	H	L	H	L	H	H	L	↑	L	H	L	H	L	L	H	L	L	L	L	L
	L	H	H	H	L	H	H	L	↑	L	H	H	H	L	L	L	H	L	L	L	L
	H	L	L	H	L	H	H	L	↑	H	L	L	H	L	L	L	L	H	L	L	L
	H	L	H	H	L	H	H	L	↑	H	L	H	H	L	L	L	L	L	H	L	L
	H	H	L	H	L	H	H	L	↑	H	H	L	H	L	L	L	L	L	L	H	L
	H	H	H	H	L	H	H	L	↑	H	H	H	H	L	L	L	L	L	L	L	H
	L	L	L	L	L	H	H	L	↑	L	L	L	L	L	H	H	H	H	H	H	H
	L	L	H	L	L	H	H	L	↑	L	L	H	L	H	L	H	H	H	H	H	H
	L	H	L	L	L	H	H	L	↑	L	H	L	L	H	H	L	H	H	H	H	H
	L	H	H	L	L	H	H	L	↑	L	H	H	L	H	H	H	L	H	H	H	H
	H	L	L	L	L	H	H	L	↑	H	L	L	L	H	H	H	L	H	H	H	H
	H	L	H	L	L	H	H	L	↑	H	L	H	L	H	H	H	H	H	L	H	H
	H	H	L	L	L	H	H	L	↑	H	H	L	L	H	H	H	H	H	H	L	H
	X	X	X	H	L	H	L	L	↑	X	X	X	H	L	L	L	L	L	L	L	L
X	X	X	L	L	H	L	L	↑	X	X	X	L	H	H	H	H	H	H	H	H	
Output Disable	X	X	X	X	X	X	X	H	X	NC	NC	NC	NC	Z	Z	Z	Z	Z	Z	Z	Z

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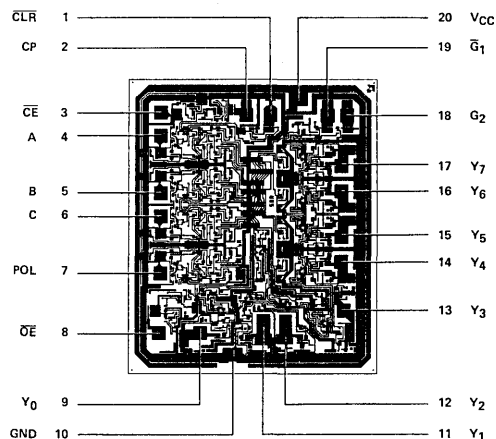
\overline{G}_1	G ₂	G
L	L	L
L	H	H
H	L	L
H	H	L

NC = No Change X = Don't Care Z = High-Impedance ↑ = Low-to-High Transition

DEFINITION OF TERMS

- \overline{CLR}** CLEAR – When the CLEAR input is LOW, the control register outputs (QA, QB, QC, QPOL) are set LOW regardless of any other inputs.
- CP** CLOCK – Enters data into the control register on the LOW-to-HIGH transition.
- \overline{CE}** CLOCK ENABLE – Allows data to enter the control register when \overline{CE} is LOW. When \overline{CE} is HIGH, the Q_i outputs do not change state, regardless of data or clock input transitions.
- A,B,C** Inputs to the control register which are entered on the LOW-to-HIGH clock transition if \overline{CE} is LOW.
- POL** Input to the control register bit used for determining the polarity of the selected output.
- \overline{G}_1** Active LOW part of the expression $G = G_1G_2$ [or $G = (\overline{G}_1)G_2$] where G is either data input for the selected Y_n or is used as an input enable.
- G₂** Active HIGH part of the expression $G = G_1G_2$.
- Y_n** The three-state outputs. When active ($\overline{OE} = \text{LOW}$), one of eight outputs is selected by the code stored in the control register, with the polarity of all eight determined by the bit stored in the POL flip-flop of the control register. The selected output can further be controlled by G according to the expression $Y_{\text{SELECTED}} = G \oplus Q_{\text{POL}}$.
- \overline{OE}** OUTPUT ENABLE. When \overline{OE} is HIGH is HIGH the Y_n outputs are in the high impedance state; when \overline{OE} is LOW the Y_n's are in their active state as determined by the other control logic. The \overline{OE} input affects the Y_n output buffers only and has no effect on the control register or any other logic.

METALLIZATION AND PAD LAYOUT



DIE SIZE 0.084" X 0.099"